

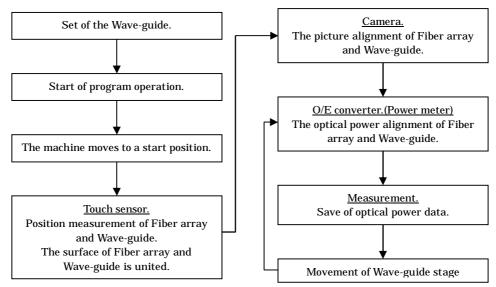
Wave-guide Measurement

High precision alignment by original high rigidity SUS stage.

High speed alignment by original power meter.

High speed alignment by original multithread software.

The main flows of the alignment system.



The program can be changed freely.





Output: Automatic Fiber array stage unit

Automatic stage = $X,Y,Z,\theta x,\theta y,\theta z$

The contact sensor is attached

(It is automatic and the surface of Fiber array and Wave-guide is united.) Picture automatic alignment camera

Center: Automatic Wave-guide stage unit

Automatic stage = X Manual stag = $Y, \theta x, \theta y, \theta z$

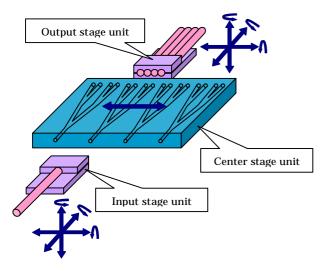
Input : Automatic Fiber array stage unit

Automatic stage = $X, Y, Z, \theta x, \theta y, \theta z$

The contact sensor is attached

(It is automatic and the surface of Fiber array and Wave-guide is united.)

Auto Motion Axes (12axes)



The move part of each unit.

	Axis	Working Range	Resolution
	LX	± 25mm	0.025 µ m
Input	LY	± 15mm	0.025 µ m
Automatic	LZ	± 25mm	0.025 µ m
Fiber array	L x	±8°	0.000015°
stage unit	L y	±8°	0.000012°
	L z	±8°	0.000012°
Center	CX	± 50mm	0.025 µ m
Center	CX RX	± 50mm ± 25mm	0.025 µ m 0.025 µ m
Center Output			
	RX	± 25mm	0.025 µ m
Output	RX RY	± 25mm ± 15mm	0.025 µ m 0.025 µ m
Output Automatic	RX RY RZ	± 25mm ± 15mm ± 25mm	0.025 µ m 0.025 µ m 0.025 µ m

The main equipment of KS502-Measurement

The main mechanism portions	The main control unit	
Input: Automatic Fiber array stage unit	LD light source (Option)ASE light source	
Automatic stage = $X, Y, Z, \theta x, \theta y, \theta z$	Selection of wavelength can be performed.	
The contact sensor is attached	O/E converter (Nch)	
Fiber array holder	Stepper motor driver (13 axis)	
Center : Automatic Wave-guide stage unit	Contact sensor driver (2ch)	
Automatic stage = Y	Computer	
Manual stag = $\mathbf{Z}, \theta \mathbf{x}, \theta \mathbf{y}, \theta \mathbf{z}$	Kuge proprietary Cockpit software	
Wave-guide holder	Stepping motor controller board	
Output : Automatic Fiber array stage unit	Picture board	
Automatic stage = $X, Y, Z, \theta x, \theta y, \theta z$	A/D board	
The contact sensor is attached	LCD monitor	
Picture automatic alignment camera	Computer rack	
Fiber array holder		
Stage unit of Observation camera.		
The observation camera and a monitor. ($\times 2$)		
Anti-vibration table and Measurement shelf		



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